

# Installation and Wiring Guide



# **Precision Products For Every Application**

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EPC- Your Encoder Solutions Partner 控制 http://www.sensor-ic.com/ TEL:0755-83376549 FAX:0755-83376182 E-MAIL:sz

#### **Company History**

Encoder Products Company Inc. (EPC) is a leading designer and world-wide manufacturer of motion sensing devices. Founded in 1969 by William Watt. EPC began operations with a small line of custom encoders. Today, more than 40 years later, EPC's popular Accu-Coder™ brand is the most complete line of incremental and absolute shaft encoders in the industry. Our core philosophy is that each and every



customer deserves quality products, superior customer service, and expert support.



### Leading The Industry By Innovation

Concentrating specifically on encoders, we have paved the path of the encoder industry, providing many of the current encoder standards. Our industry leading advancements include the Cube™ style encoder, flex-mount system used on hollow-bore encoders, Opto-ASIC technology for enhanced signal quality, 120° C operating temperature for extreme environments, 6000 CPR in a 1.5" diameter encoder, a three year standard warranty, and many others.

#### **Custom Encoders Our Specialty**

Through years of experience, we understand each industrial environment is different, and customize encoders for your specific situations. Many of our customers depend on EPC to provide encoders which fit their specifications, not someone else's. Using state of the art technology, we can design and deliver custom encoders faster than most suppliers standard products - often shipping your unique encoder in 2 to 6 days, or sooner. Plus, with ISO 9001:2008 quality



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Congratulations on your purchase of a genuine EPC Accu-Coder™ brand encoder. Every Accu-Coder™ is built to exact standards, and thoroughly tested during the manufacturing process. Improper installation is the major cause of most common problems. By following the guidelines given in this pamphlet, we hope to eliminate any problems before they start, thus providing the maximum life from your encoder. Properly installed and cared for, your Accu-Coder™ will give you years of trouble free use. Technical Bulletins, which provide general encoder information, and cover specific installations, can be found under the "Support" heading on www.encoder.com. If you have any questions concerning installation, please feel free to call Customer Service @ 1-800-366-5412. Thank you!

#### WARRANTY INFORMATION

Your Accu-Coder™ is guaranteed against defects in materials, and workmanship by the best three year standard warranty in the business. The warranty applies to all standard catalog products starting three years from the date of shipment. To learn more about our three year standard warranty, go to **www.encoder.com**, under the "Support" menu, select "Warranty."

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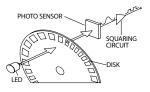
#### **ENCODER BASICS**

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direction. As the encoder shaft rotates, output signals are produced, proportional to the distance (angle) of rotation. The signal may be in the form of a square wave (for an incremental encoder) or an absolute measure of position (for an absolute encoder).

Due to the performance and reliability advantages of the semi-conductor technology they incorporate, optical encoders are the preferred solution in many common computer, industrial, and automotive applications. Optical encoders also benefit from ease of customization, are suitable to numerous environments, and suffer no effects from high levels of stray magnetic fields.

The basic construction of an incremental encoder is shown to the right. A beam of light emitted from an LED passes through a transparent disk patterned with opaque lines, and is picked up by a photodiode array. The photodiode array (also called a photosensor) responds by producing a sinusoidal waveform which is transformed into a square wave, or pulse train.



Incremental encoders are available in two basic output types, single channel and quadrature. A single channel encoder, often called a tachometer, is normally used in systems that rotate in one direction only, and require simple position and velocity information. Quadrature encoders have dual channels (A and B), phased 90 electrical degrees apart. These two output signals determine the direction or rotation by detecting the leading or lagging signal in their phase relationship. Quadrature encoders provide very high speed bi-directional information for very complex motion control applications.

Incremental encoders can provide a once-per-revolution pulse (often called index, marker, or reference) that occurs at the same mechanical point of encoder shaft revolution. This pulse is on a separate output channel (Z) from the signal channel or quadrature outputs. The index pulse is often used to position motion control applications to a known mechanical reference.

#### **ACCESSORIES**

illands to design from the commentation of the comment of the comm that does not. EPC offers a range of accessories that are designed to not only make your life easier, but are manufactured to EPC's high standards, ensuring years of trouble free

service. In addition, they have been tested with the products they complement, so that you do not have to worry about proper form, fit, or function.



#### Connectors/Cables

High quality connectors, cables, cable assemblies, and cord sets selected to optimize encoder performance; most can be ordered with MS style or M12 connectors.



#### Shaft Couplings

Precision shaft couplings to optimize performance and reduce the chance of premature failure; designed to restrict the transfer of thermal and mechanical stress; wide range of choices to match your exact requirement. Call about our new Magnetic Coupling!



#### **Protective Covers**

Covers help protect encoders from damage. They also allow a wider variety of encoders to be used in harsh environments.



#### **Hub/Flanges**

Allow Accu-Coder™ encoders to be easily mounted to industry standard housing styles; NEMA, servo, 5PY, and other styles available; rugged, reliable construction.



#### Mounting Brackets

Used to mount measuring wheels to Cube and 702 Series Accu-Coders<sup>TM</sup>. Two types: single pivot and dual pivot; single pivot pivots vertically while dual pivot pivots vertically and longitudinally.



#### Measuring Wheels

Used to obtain linear motion feedback from a rotating shaft: range of surface finishes (urethane, rubber, knurled, grooved) for proper mating to nearly any application surface; available in several sizes to allow you to satisfy your exact requirements.



#### Linear Cable Adapter

The linear cable adapter (LCA) used with a Cube Series standard or industrial housing, provides a low cost alternative for obtaining

#### MOUNTING AND MECHANICAL INSTALLATION

bolts to their recommended torque. Remember, tighter isn't always better!

空制 http://www.sensor-ic.com/ TEL:0755-83376549 FAX:0755-83376182 E-MAIL:sz For over 40 years, our engineers have been designing encoders that are quick and easy to install. With a variety of mounting options available, your encoder should be a perfect match for your existing equipment. Accessories such as pivoting mounting brackets, measuring wheels, flexible couplings, etc., are available from EPC to ease installation. The first principle for every encoder installation is "Don't force it!". Striking or using excessive force can either damage your new encoder, or introduce excessive shaft loading.

shaft misalignment, or other conditions shortening its expected life. Tighten all couplings and

### Shaft Style Encoders



- Gently couple the shaft of the Accu-Coder™ to the driving shaft, using a correctly sized flexible shaft coupling.
   Never use a rigid coupling.
- Verify proper alignment between the Accu-Coder™ shaft and the driving shaft.
- If using pulleys or gears, mount them on the shaft as close as possible to the Accu-Coder<sup>TM</sup> to reduce bearing load.
- Axial and radial shaft loading should be low as possible.
   Never exceed printed specifications.
- Use recommended torques to tighten all clamping bolts and couplings.

#### Hollow Bore Encoders



- · Make sure driving shaft is free from burrs and other defects.
- With flex mount flush against surface, tighten clamp or set screws first, then bolt flex mount to surface.
- Check for best possible alignment with hollow shaft and driving shaft to reduce wobble.
- Runout of the driving shaft, or misalignment between the driving shaft and the encoder's hollow bore, decreases the accuracy and bearing life of the encoder and adds vibration to the system. Re-installing the encoder on the driving shaft may improve alignment.

### C-Face Style Encoders



- Verify that mounting holes are in exact alignment with holes or studs on the motor frame.
- Tighten all fasteners with equal torque so as not to distort the shape of the ring.

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# Caution: Avoid damage to your Accu-Coder™. The following চাইকী http://ˈaʊtɪoᠠᠬᠲᠬᠠᠷay-dauseখaᠬᠮᠮage,7करित ೪४३/विकिरित พืळानिकारु.376182 E-MAIL:sz

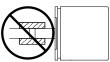


Do not shock or strike.





Do not subject shaft to excessive axial or radial shaft stresses.



Do not use a rigid coupling.

# Do not disassemble. RECOMMENDED BOLT TORQUES

MODEL	STYLE	DESC./LOCATION	THREAD	TORQUE	HEX KEY
15T/H	All	Set Screws / Shaft	M3	30 to 45 oz-in	1.5 mm
25T/H	Clamp	Clamp Bolt	6-32	10 to 15 lb-in	7/64"
225	All	Set Screws / Shaft	6-32	30 to 40 oz-in	1/16"
260, 960	Clamp	Clamp Bolt	2-56	100 to 120 oz-in	5/64"
1702	Flex Hollow	Set Screws / Shaft	6-32	50 to 80 oz-in	1/16"
102	Flex Hollow	Clamp Bolt / Shaft	4-40	115 to 160 oz-in	3/32"
	Flex Hollow	Set Screws / Shaft	6-32	35 to 50 oz-in	1/16"
755	Flex Hollow	Set Screws / 0.75" Shaft	4-40	25 to 40 oz-in	0.050"
770	Collet	Cup / Cone Bolts	4-40	120 to 200 oz-in	3/32"
774	1.0" up to 1.375"	Clamp Bolt	8-32	30 to 35 lb-in	9/64"
771	>1.375" to 1.875"	Clamp Bolt	6-32	15 to 25 lb-in	7/64"
775	Collet	Cup / Cone Bolts	4-40	120 to 200 oz-in	3/32"
113	Clamp	Clamp Bolt	8-32	30 to 35 lb-in	9/64"
776	Clamp	Clamp Bolt	6-32	15 to 25 lb-in	7/64"
770, 775, 776	All	Protective Cover	4-40	70 to 120 oz-in	3/32"
771	All	Protective Cover	3/8"-16	180 to 240 lb-in	5/16"
TR1, TR2	All	Pivot Bolt/Shaft	1/4"-20, M6	40 to 60 lb-in	5/32"
IKI, IKZ	All	Set Screw/Torque Adj	10-32	15 to 18 lb-in	3/32"
TR1	All .	Set Screw/Wheel	4-40	25 to 40 oz-in	0.050"_
†pp://ww	WASensor-IC.	COM/Screwpinion/55-83	3669 <u>4</u> 89 F	A%5Q/565z833/	161/82° E-

10-32

10-32

35 to 40 lb-in

30 to 35 lb-in

Set Screw/Wheel

Spring Pivot Clamp

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3/32"

5/32

TR3

ΑII

All

#### ELECTRICAL CONNECTION

5控制 http://www.sensor-ic.com/ TEL:0755-83376549 FAX:0755-83376182 E-MAIL:sz Proper wiring and grounding are essential for the longevity and proper operation of your

Accu-Coder\*\*. In addition, electrical noise should be minimized to prevent improper counts and/or damage to the electronic components.

Since an Accu-Coder™ can be used with a wide variety of input devices (PLC's, counters, servo controllers, etc.), from many different manufacturers, it is important to determine proper wiring and connections before installation.

#### **Common Signals**

Most Accu-Coder™ encoders have the following electrical connections:

Power, Common or Ground, and one or more Output Signals.

**Power** (Also called supply, power source, encoder power, +V, or +VDC)

- · Always use a direct current (DC) voltage.
- Attach power to the positive (+) side of the power source.
- Verify that the Accu-Coder™ is receiving the proper voltage, since most electrical failures are caused by an improper or improperly regulated power source.
- The use of surge protection is highly recommended.

#### **Common** (Also called Com, supply common, and ground)

• Attach common to the negative (-) side of the power source.

#### Output Signals (Always at least one, but may be as many as six)

- The most common are A, B, and Z. Commutation outputs include U, V, and W.
- Encoders with a Line Driver output also have the complement (A and A', B and B', etc.) as separate outputs that are used to provide differential signals for reduced noise and greater drive capability.
- Never connect the output signals together, or to the power source!

#### Connections

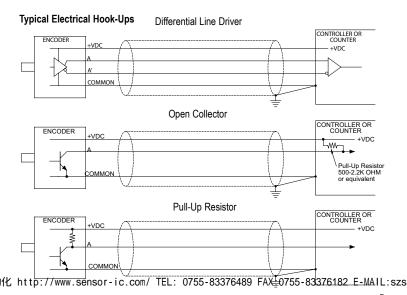
- · Verify and match up pin numbers, wire colors, or terminal blocks with the input device.
- Be aware that identification terminology may not always be identical.
- Once proper wiring is determined, document it for future reference.

#### Cable Routing

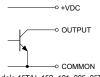
- Cable length should be minimized by using the shortest route possible.
- All cabling should be installed in dedicated metal conduits, or located at least 12" away from other wiring.
- Route cables away from high current conductors to minimize pulses caused by electrical transients.
- Signal wire continuity should be maintained from the encoder to the controller/counter.

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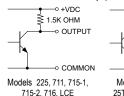
- Noise can be generated by solenoids, relays, motors, starters, and similar devices.
- Using shielded cables will dramatically reduce the effects of noise. Most Accu-Coder™
  cables are double shielded (foil and braid) for optimum protection.
- Ensure all equipment is properly grounded. (Motors, drives, shafts, etc.)
- Connect encoder cable shield to ground at controller/counter end, leaving the end near the encoder unconnected. Connecting the shield at both ends can cause ground loops, and improper operation.
- If possible, use differential line driver outputs with high quality shielded, twisted
  pair cable. (Complementary signals greatly reduce common mode noise levels, as well
  as signal distortion resulting from long cable lengths.)
- EPC's line of Repeaters and Converters may help reduce the effects of electrical noise.



#### **OUTPUT CIRCUIT DIAGRAMS**



Models 15T/H, 15S, 121, 225, 25T/H, 260, 702, 711, 715-1, 715-2, 716, 725, 755A, 758, 770, 771, 775, 776, 802S, 858S, 925, 958, 960, LCE, TR1, TR2



Models 15T/H, 15S, 25T/H, 702, 725, 755A, 758, 770, 771, 775, 776, 802S, 858S, TR1, TR2

+VDC

OUTPUT

COMMON

2.2K OHM

#### Line Driver (HV, H5)



Models 15T/H, 15S, 121, 25T/H, 260, 702, 711, 716, 725, 755A, 758, 770, 771, 775, 776, 802S, 858S, LCE, TR1, TR2

### Push-Pull (PP, P5)



Models 15T/H, 15S, 121, 25T/H, 260, 702, 711, 716, 725, 755A, 758, 770, 771, 775, 776, 802S, 858S, 925, 958, 960, LCE, TR1, TR2

Does your application require signals to be transmitted long distances, or is your signal incompatible with interfacing equipment?

EPC's RXTX Repeater incorporates a Differential Line Receiver on its input, along with a Differential Line Driver at the output. The Line Receiver provides common mode noise rejection, helping to reduce the noise and

common mode noise rejection, helping to reduce the noise ar distortion associated with long cable runs in a plant environment. A Line Driver adds current drive capacity allowing transmission of clean signals over much longer distances. Several RXTX Repeaters can be cascaded, if necessary, for extremely long cable runs. The RXTX Converter is designed to convert differential signals to single ended signals, and vice versa. It can be used to convert to differential signals for long cable runs, or simply to convert to



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#### INCREMENTAL ENCODER WIRING TABLES

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PM12	CONNEC	TORSENSO	IT-IC.COM/ TEL:
	8	PIN	5 PIN
	15S, 15T/H 260, 702, 72	k 2, 716, LCE, , 25T/H, 225A/Q, 25, 755A, 758, 75, 776, TR1,	711, 715-1& 2, 716, LCE, 15S, 15T/H, 25T/H, 225A/C 260, 702, 725, 755A, 758, 770, 771, 775, 776, TR1, TR2, TR3
	HV, H5	O, OC, S, PU, PP, P5	O, OC, S, PU PP, P5
Pin	Func	Func	Func
1	Α	Α	+VDC
2	+VDC	+VDC	В
3	A'		Com
4	В	В	Α
5	B'		Z
6	Z	Z	
7	Com	Com	-
8	Z'		

CE Option: Read Technical Bulletin "TB111" at www.encoder.com

D-SUB MINIATURE
(9-pin) CONNECTORS

6 Z 7 Z' 8 Case\*

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(3-pin) CONNECTONO										
	702, 725	, 775, 776	225A	225Q						
	HV, H5	OC, PU,	OC, PU	OC, PU						
		PP, P5								
Pin	Func	Func	Func	Func						
1	+VDC	+VDC	+VDC	+VDC						
2	Α	Α	Α	Α						
3	A'	-								
4	В	В		В						

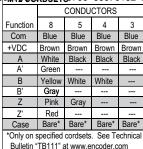
9 Com Com Com Com

\*702, 725 Pin \* is Always connected to Case

\*775, 776 Non-CE Option: Pin 8 has No
Connection. CE Option: Pin 8 is connected

Case\*

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MS CONNECTORS									
	10-PIN	7-1	6-PIN						
	711, 716,LCE, 25T/H, 702, 725, 758, 770, 771, 775, 776	25T/H, 758, 7	16, LCE, 702, 725, 70, 771, 5, 776	711, 716, LCE	711, 715-1/-2, 716, LCE, 25T/H, 702, 725, 775, 776				
	HV, H5	HV, H5	O, OC, S, PU, PP, P5	HV (No Index)	O, OC, S, PU, PP, P5				
Pin	Func	Func	Func	Func	Func				
Α	Α	Α	Α	Com	Com				
В	В	В	В	+VDC	+VDC				
С	Z	A'	Z	Α	Z				
D	+VDC	+VDC	+VDC	A'	Α				
Е	-	B'		В	В				
F	Com	Com	Com	B'	Com				
G	Case*	Case*	Case*						
Н	A'	-							
	B'								
J	Z'								

\*711, 716, LCE, 25T/H, 702, 725, 758-

Pin G is Always connected to Case \*770, 771, 775, 776- Non-CE Option:

0755 - 83376489 to EANe d0755 - 83378 82 CE Option: Pin G is connected to Case



# INCREMENTAL ENCODER WIRING TABLES (Continued)



	15T/H, 15S, 121, 25T/H, 260, TR1, TR2						711, 715- 716,		225A	225Q
	HV, OC, LO	OC, PP, PU	HV, H5, OC, PU, PP, P5	HV, H5, OC, PU, PP, P5	HV	O, OC, S, PU, PP	OC, PU,	OC, PU,		
Func	Wire	Wire	Wire	Wire	Wire	Wire	Wire	Wire		
FullC	Color	Color	Color	Color	Color	Color	Color	Color		
Com	Black	Black	Black	Black	Black	Black	Black	Black		
+VDC	White	White	White	Red	Red	Red	Red	Red		
Α	Brown	Brown	Brown	White	White	White	White	White		
A'	Yellow		Yellow	Brown	Brown					
В	Red	Red	Red	Blue	Blue	Blue		Green		
B'	Green		Green	Violet	Violet					
Z	Orange	Orange	Orange	Orange	Orange	Orange				
Z'	Blue		Blue	Yellow	Yellow					
U	Violet	Violet								
U'	Gray									
V	Pink	Pink								
V'	Tan									
W	Red/Grn	Red/Grn								
W'	Red/Yel									
Case				Green**	Green***					
Shield	Bare*	Bare*	Bare*	Bare*	Bare*	Bare	Bare	Bare		

<sup>\*</sup>CE Option: Cable shield (bare wire) is connected to internal case

<sup>\*\*\*</sup>E-Cube Only

TERMINAL BLOCK										
							711, 715-1,			
177		770,	771	755A	225A	225Q	715-2, 7	16, LCE		
				HV, H5,			HV	O, OC,		
		HV	OC, PU,	OC, PU,	OC, PP	OC, PP	No	S, PU,		
			PP	PP, P5			Index	PP, P5		
	Pin	Func	Func	Func	Func	Func	Func	Func		
	1	+VDC	+VDC	Α	Com	Com	Com	Com		
	2	Com	Com	A'	+VDC	+VDC	+VDC	+VDC		
	3	Α	Α	В	Α	Α	Α	Z		
	4	A'		B'		В	A'	Α		
	5	В	В	Z			В	В		
	6	B'		Z'			B'	Com		
	7	Z	Z	Com				-		
	8	Z'		+VDC						

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<sup>\*\*</sup>Only on Models 702, 725, 758, 802S, 858S

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MISC OF HONS								
		12 Pin		8 PIN	10 PIN INI	DUSTRIAL	10 PIN B	AYONET
		(ccw pir	n layout)	MOLEX	CLA	MP		
		7	58	755A	770,	771	25T/	H, 702
12-pin		HV, H5	OC, PU PP, P5	LD, OC, PU, PP	HV OC, PU,		HV, H5, OD, PU, PP, OC, P5	
	Pin	Func	Func	Func	Func	Func	Pin	Func
	1	B'		+VDC	Com	Com	F	Com
	2	+VDC Sense	+VDC Sense	Com	В	В	D	+VDC
	3	Z	Z	B'	Α	A Z	Α	Α
8-pin Molex	4	Z'		В	Z	Z	Н	A'
o-piri iviolex	5	Α	Α	Z'			В	В
	6	A'		Z	+VDC	+VDC	J	B'
2	7			A'	B'		С	Z
	8	В	В	Α	A'		K	Z'
	9	Case	Case		Z'		G	Case
	10	Com	Com		Case*	Case*		
10-pin Industrial	11	Com Sense	Com Sense					
Clamp	12	+VDC	+VDC					
	*CE Option Only							

3xx EN	3xx ENCODER CABLE ASSEMBLIES											
		STANDARD										
		PIN IS	7-PI	N MS	6-PII	N MS	9-PIN	D-SUB	12-	PIN	10- BAYO	PIN ONET
Function	HV	ST	HV	ST	HV	ST	HV	ST	HV	ST	HV	ST
Com	Black	Black	Black	Black	Black	Black	Black	Black	Black	Black	Black	Black
+VDC	Red	Red	Red	Red	Red	Red	Red	Red	Red	Red	Red	Red
Α	White	White	White	White	Orange	White	White	White	White	White	White	White
A'	Brown	-	Brown		White	-	Brown		Brown		Brown	-
В	Blue	Blue	Blue	Blue	Green	Green	Blue	Blue	Blue	Blue	Blue	Blue
B'	Violet		Violet		Blue		Violet		Violet		Violet	
Z	Orange	Orange	1	Orange	-	Orange	Orange	Orange	Orange	Orange	Orange	Orange
Z'	Yellow				-		Yellow		Yellow		Yellow	
Case	Green	Green	Green	Green					Green	Green	Green	Green
Shield	Bare*	Bare*	Bare*	Bare*	Bare*	Bare*	Bare*	Bare*	Bare*	Bare*	Bare*	Bare*
Com Sense		I	1		-	I			Gray	Gray	-	1
+VDC Sense		-	-			1			Pink	Pink		-

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### ABSOLUTE ENCODER WIRING TABLES

京控制 (http://www.sengon tc.com/ TEL:0755-βββββξωβξωβκ:0755-83376182 E-MAIL:sz KPT 02E14-19P Mating Conn. 925, 958 925, 958 925, 958 925 Function Wire Color NOTES: Pin Pin Pin S1 MSB Brown Only available with 8-Α 3 Α S2 White bit resolution encoders 5 R S3 \*\* Where Fitted C Green 6 S4 7 Orange \*\*\* Direction Control-S5 Е Blue 8 F Standard is CW increasing S6 9 Violet when viewed from the F S7 Gray shaft end. Direction pin is 10 G S8 LSB 8-bit Н 11 Н Pink pulled high normally to 5V S9 LSB 9-bit Red/Green internally. Direction pin J 12 S10 LSB 10-bit Red/Yellow must be pulled low K 13 S11 LSB 11-bit Turquoise (GND, Common) to reverse 14 S12 LSB 12-bit count direction. Applied M 15 Yellow Direction\*\*\* R Red/Blue voltage to direction pin 4 Case Ground Drain/Screen S should not exceed 5V 16 0V Common Black 1 J. Special\*\* White/Red U +VDC Red

		Gland Cable	
		960	1
	Function	Wire Color	N
	Common	Black	* (
	+VDC	Red	** 5
	S1 cw MSB	Brown	۱ f
	S1 ccw MSB	Yellow	] †
	S2	White	۱ ۱
	S3	Green	ľ
	S4	Orange	1
	S5	Blue	(
	S6	Violet	١
	S7	Gray	١
	S8 LSB 8-bit	Pink	١
	S9 LSB 9-bit	Red/Green	
	S10 LSB 10-bit	Red/Yellow	
	S11 LSB 11-bit	Turquoise	]
/// h.t.m./	Direction Control**	Red/Blue	<u>ل</u> ے
化 http://	Case Ground - 1 C	· Cathleld I E L .	ν/:

## OTES:

CE Option Only

Standard is CW increasing count (when viewed from shaft end, and using brown wire for MSB). Red/Blue is pulled up internally to 5 VDC. To reverse count dirction, RED/Blue must be pulled low (0 VDC). If 5VDC is appplied to Red/Blue, unit remains in standard CW increasing count mode. Count direction can also be reversed by using the Yellow MSB wire instead of the Brown. At no time should voltage applied to Red/Blue exceed 5 VDC.

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#### TROUBLESHOOTING .

- If there is no mechanical movement, there will be no output. Therefore, verify that the Accu-Coder™ is rotating.
- Check to make sure the proper supply voltage is present. It is best to do this at the Accu-Coder™ end, if possible.
- Verify all wiring between the Accu-coder™, the counter/controller, and the power supply.
- Make sure that the proper signal type (OC, PU, LD, PP) is being used for the application.
- Verify that the counter/controller is properly installed and operational. Consult the appropriate User's Manual if necessary.
- If another Accu-Coder™ is available, try it to determine if the encoder is the problem.

#### Erratic Output/Missing or Extra Counts

- Electrical: Check for loose wiring connections, ground loops, encoder outputs incompatible with the counter/controller, a noisy power supply, electrical noise, proper termination of shields, or a combination of these problems.
- Mechanical: Check for improper alignment, loose coupling, or, if used, slippage in the measuring belt or wheel.

#### **Counts Indicate Wrong Direction**

- Check for reversed wiring of the quadrature signals. Reverse if needed.
- If differential signals are being used, make sure that both sides are properly wired.
- Note: If an index pulse is being used, reversing the wiring will cause the reference alignment to change.

#### **Counts In Only One Direction**

- Make sure that the counter/controller is capable of, and programmed for, bi-directional counting.
- On quadrature units, both channels (A and B) must be present and operational. Check by using a dual channel oscilloscope.
- Make sure the input selection type programmed into the counter/controller, matches the Accu-Coder™. If there is a mis-match, the system may not work properly.

#### Index Pulse Not Working

- The index pulse occurs only once per revolution, and can be difficult to check with a volt meter. Check index pulses with an oscilloscope.
- The counter/controller may not be capable of detecting the index pulse at higher RPM's. Slowing down the rotation may allow for detection of the index pulse.

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