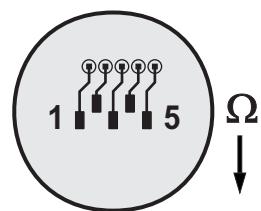
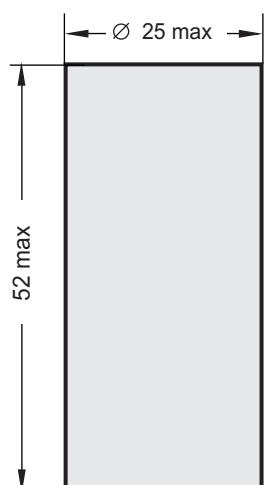
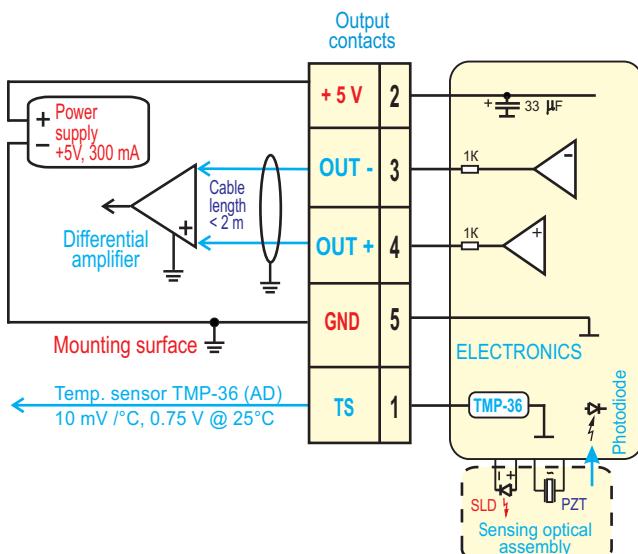


OUTLINE DRAWING



CONNECTION DIAGRAM



PHYSICAL PARAMETERS

1. Ω - sensing axis
2. Dissipation - 0.8 W
3. Weight - 30 gram
4. Volume - 0.025 litre
5. Housing material - aluminum alloy (option - plastic)
6. Housing protection - anodizing
7. Tolerances per ISO 2768-m
8. Ingress protection class - IP67

MAIN PARAMETERS (typical values)

♦ Rate range	50 deg/s
Scale Factor (SF)	35 mV/deg/s
Frequency range	0... 1 kHz
Angle random walk	0.015 deg / $\sqrt{\text{h}}$
Bias stability, RMS	2 deg / h
SF stability, RMS	0.03 %
Readiness time	0.02 s

ENVIRONMENT

Temperature operating endurance	-40°C ... +70°C
Vibration (operating), RMS	6 g, 20Hz... 2000Hz
Vibration (endurance), RMS	12 g, 20Hz... 2000Hz
Shocks (endurance)	150 g, 1 ms
Acceleration (operating)	5 g
Acceleration (endurance)	20 g, 5 s

RELIABILITY

MTBF	60000 hours (20°C, predicted)
♦♦ Lifetime (predicted)	15 years
♦ Precision class - ④	
♦♦ Estimated for low humidity	

DESCRIPTION OF OUTPUT CONTACTS

Contact	Name	Comments
1	TS	Output of temperature sensor (TMP-36) 10 mV per deg.C; 0.75V at 25 deg.C
2	+ 5 V	Power input + 5V ± 0.25V, 200mA max, ripple 10mV max within 0-1MHz
3	OUT -	Analog output (~ 17.5 mV/°s), * 1V biased to "GND"
4	OUT +	Analog output (~ 17.5 mV/°s), * 1V biased to "GND"
5	GND	Power return line, ground.

* - sensor's output is a difference between the voltages at 4 and 3 contacts

RECOMMENDATIONS AND PRECAUTIONS

1. Do not deform housing
2. Fragile components inside - no shocks, no drop
3. Treat as electrostatic sensitive unit
4. Is designed to be mounted inside water protected equipment
5. Increased humidity shortens essentially lifetime
6. Mounting surface must be grounded
7. Power must be off during connecting
8. Soldering to contacts - by low-temperature solder