

### Function principle

Magnetoresistive materials can change their resistivity in an external magnetic field. The variation of the resistivity is determined by the rotation of magnetisation with respect to the direction of the current flow. Permalloy ( $Ni_{81}Fe_{19}$ ) is commercially used as magnetoresistive material. The relative change of resistivity is 2-3 % for this material. The high sensitive and small size magnetoresistive sensor consists of the chip 174B coated with thin film permalloy stripes. These stripes form a Wheatstone bridge, whose output voltage is proportional to the magnetic field component  $H_y$ .

### Characteristic

The bridge imbalance is a value for the magnetic field component  $H_y$  in the plane of the chip. It is of advantage to apply an auxiliary field  $H_x = 3 \text{ kA/m}$  which avoids flipping of the magnetisation of the stripes caused by disturbing magnetic fields. A perpendicular field  $H_x$  is necessary to stabilize sensor operation. This can be done by using a small permanent magnet. Magnetic fields vertical to the chip surface have no influence on the output voltage.

### Special feature

In contrast to KMY 20 S, sensor KMY 20 M features a permanent magnet integrated in the housing. The compact sensor is ready to use. No external auxillary fields are required for safe operation in a disturbing field up to 30 kA/m.

## Sensors in thin film technology

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#### Technical data

### **Absolute maximum ratings**

<b>Parameter</b>	<b>Symbol</b>	<b>Unit</b>	<b>Value</b>
<i>Supply voltage</i>	$V_B$	V	12
<i>Total power dissipation</i>	$P_{\text{to}}$	mW	120
<i>Operating temperature range</i>	$T_{\text{amb}}$	°C	-40 ... + 125
<i>Storage temperature range</i>	$T_{\text{stg}}$	°C	-65 ... +150
<i>Disturbing field</i>	$H_d$	kA/m	≤ 30

### **Electrical characteristics ( $T_{amb} = 25^\circ\text{C}$ )**

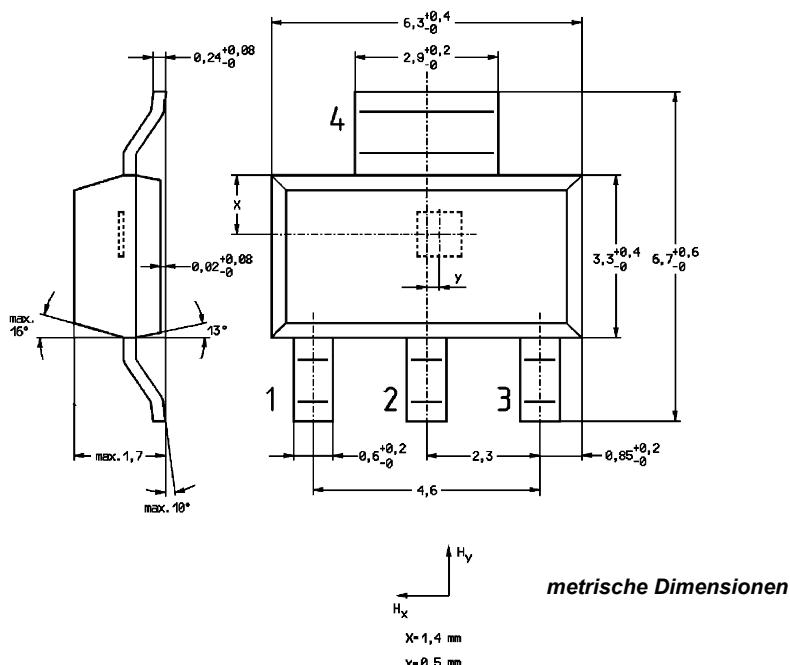
Parameter	Symbol	Unit	Value
Bridge resistance	$R_B$	kOhm	1.4 .. 2.2
Open circuit sensitivity	$S_V$	(mV/V)/(kA/m)	$5.5 \pm 1.5$
Output voltage range	$\Delta V_O / V_B$	mV/V	$18.0 \pm 4.0$
Hysteresis of output voltage	$V_{O_H} / V_B$	$\mu$ V/V	$\leq 50$
Offset voltage	$V_{OFF} / V_B$	mV/V	$\leq \pm 1.5$
Permanent auxiliary field	$H_x$	kA/m	$1.5 \pm 0.4$

#### **Temperature coefficients (- 25 °C < $T_{amb}$ < 125 °C)**

of

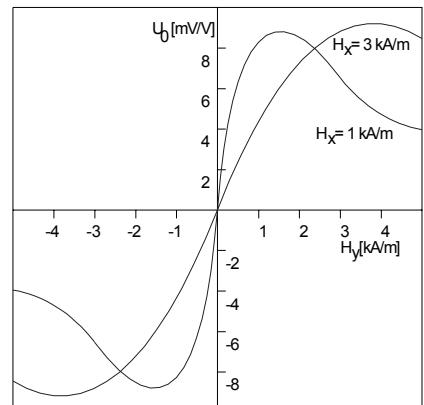
Parameter	Symbol	Unit	Value
Bridge resistance	$T_{CBR}$	%/K	$0.30 \pm 0.05$
Open circuit sensitivity ( $V_B = \text{const}$ )	$T_{CSV}$	%/K	$-0.25 \pm 0.05$
( $I_B = \text{const}$ )	$T_{CSI}$	%/K	$0.05 \pm 0.05$
Offset voltage	$T_{COFF}$	$(\mu\text{V}/\text{V})/\text{K}$	$\leq \pm 3$
Difference of offset voltage for sensor pair	$\Delta T_{COFF}$	$(\mu\text{V}/\text{V})/\text{K}$	$\leq \pm 0.5$

**Hausing KMY 20:** SOT-223-S



## Applications

- detection of weak magnetic fields,  
e.g. earth magnetic field
  - contactless mechanical switch
  - displacement measurement with  
high resolution
  - revolution speed detection  
on ferromagnetic gear wheels
  - contactless angle measurement
  - galvanically separated current  
measurement



*Output voltage versus field component  $H_y$  for different stabilizing magnetic fields  $H_x$*

2 KMY 20 M

We also offer selected pairs of KMY 20 M. These pairs have a similar temperature characteristic of the voltage offset and are well suited for differential measuring techniques. The temperature drift of the magnetoresistive sensor is strongly reduced by applying this technique.

**SOT-223-S**  
 1: + $V_0$  2: - $V_0$      $V_0$ : Ausgangsspannung  
 3: + $V_B$  4: - $V_B$      $V_B$ : Betriebsspannung

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