

Correvit® S-HR Sensors

Non-Contact Optical Sensors

Type CSHRA...

Patent No. 44 44 223 C5
DE 10 2007 008 004 B4

The Correvit S-HR sensors are an advancement of the proven 2-axis Correvit sensors and feature a high-resolution, low-noise angle signal.

- Correvit S-HR with working range 250 ±50 mm, applicable from 0,5 ... 250 km/h
- Accuracy of the unfiltered angle within the range of ±15 ° is ±0,1 °
- High-resolution slip angle measurement by enhanced measuring principle
- Adjustable filter time (unfiltered, moving average 8 ... 512 ms, FIR-Filter 2 ... 100 Hz)
- Extremely high measurement accuracy, better than ±0,2 %, as a result of precise optics and digital signal processing
- Signal outputs: Analog, Digital, CAN-Bus, USB, RS-232C

Description

Correvit S-HR sensors measure slip angle and sideslip angle with high dynamics and an exceptionally high measurement accuracy.

The patented enhancement of the well-known Correvit principle, the application of new optical components, and the latest technology in digital signal processing enable the most precise high-resolution slip angle measurement. True 250 Hz signal update rate tracks every high dynamic maneuver.

Due to the new operating principle (absolute measuring) the angle signal is very low-noise which provides maximum dynamic performance of the angle signal without further signal filtering. This advantage make the sensors especially suited for measuring transversal vehicle dynamics like sideslip angle but also tire slip angle when mounted on wheel.

The new Correvit S-HR sensors represent an essential contribution to the development of automotive measuring engineering.

Application

High-precision, slip-free measurement of distance, longitudinal/transversal speed and angle (high-resolution) for dynamic vehicle testing, e.g. ISO 4138 steady-state circular-course driving, ISO 7401 sudden steering angle change, tire research.



Technical Data

Performance Specifications

| | | |
|------------------------------------|------|-------------|
| Speed range | km/h | 0,5 ... 250 |
| Angle measurement range | ° | ±40 |
| high-resolution | ° | ±15 |
| Distance resolution | mm | 2,66 |
| Measurement accuracy ¹⁾ | %FSO | <±0,2 |
| Range high-resolution angle output | km/h | 10 ... 250 |
| Angle resolution | ° | <0,01 |
| Angle accuracy | ° | <±0,1 |
| Measurement frequency | Hz | 250 |
| Working distance and range | mm | 250 ±50 |

Signal Outputs

| | | |
|--|----------|-----------------|
| Digital output 1 - IVI or V _l ²⁾ | Pulses/m | 1 ... 1 000/TTL |
| Digital output 2 - V _q or angle ²⁾ | kHz | 0 ... 46/TTL |
| Analog output 1 - IVI or V _l ²⁾ | V | 0 ... 10 |
| Analog output 2 - V _q | V | -10 ... 10 |
| Analog output 3 - angle | V | -10 ... 10 |

Signal Inputs

| | | |
|------------------|-----|------------|
| Trigger input | | yes |
| Analog input 1+2 | V | -10 ... 10 |
| Counter input | kHz | 0 ... 100 |

Interfaces

| | | |
|----------------------|--|------|
| CAN (Motorola/Intel) | | 2.0B |
| USB (Full Speed) | | 2.0 |
| RS-232C | | yes |

¹⁾ determined on test surface with distance >200 m

²⁾ Switching-over between the respective measured variables via CeCalWin Pro possible

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This information corresponds to the current state of knowledge. Kistler reserves the right to make technical changes. Liability for consequential damage resulting from the use of Kistler products is excluded.

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Technical Data (Continuation)

System Specifications

| | | |
|-------------------------------------|-------|--------------|
| Power supply | V | 10 ... 28 |
| Power consumption at 12 V | W | 60 |
| Temperature range | | |
| Operation (ambient temperature) | °C | -5 ... 50 |
| Storage | °C | -10 ... 85 |
| Relative humidity (non-condensing) | % | 5 ... 80 |
| Protection standard (cable mounted) | | |
| Sensor head | | IP67 |
| Electronics | | IP30 |
| Dimensions (LxWxH) | | |
| Sensor head (with spray guard) | mm | 165x50x130 |
| Electronics | mm | 180x125x95 |
| Weight | | |
| Sensor head (with spray guard) | grams | 1 250 |
| Electronics | grams | 1 250 |
| Shock | g | 50 half-sine |
| | ms | 6 |
| Vibration | g | 10 |
| | Hz | 10 ... 150 |
| Illumination | | Halogen |

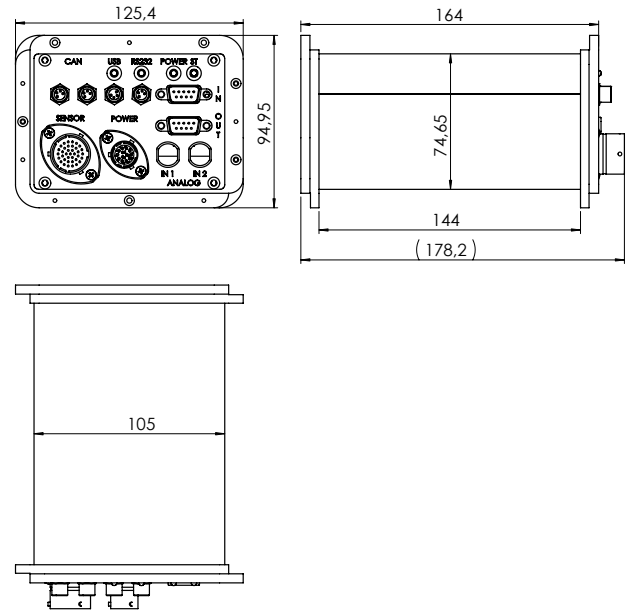


Fig. 2: Dimensions Correvit® S-HR electronics

Dimensions

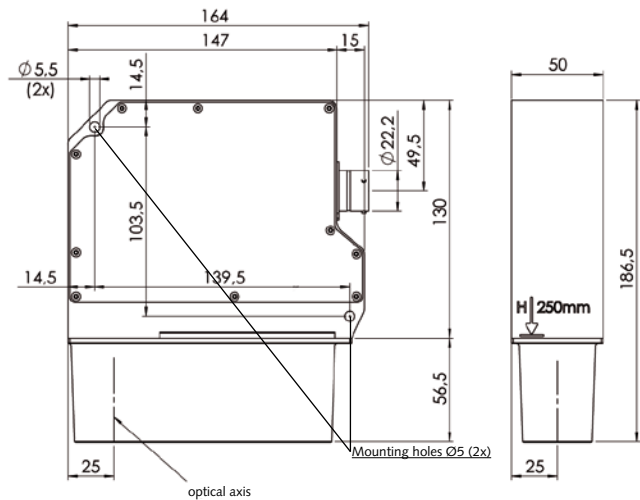


Fig. 1: Dimensions Correvit® S-HR sensor

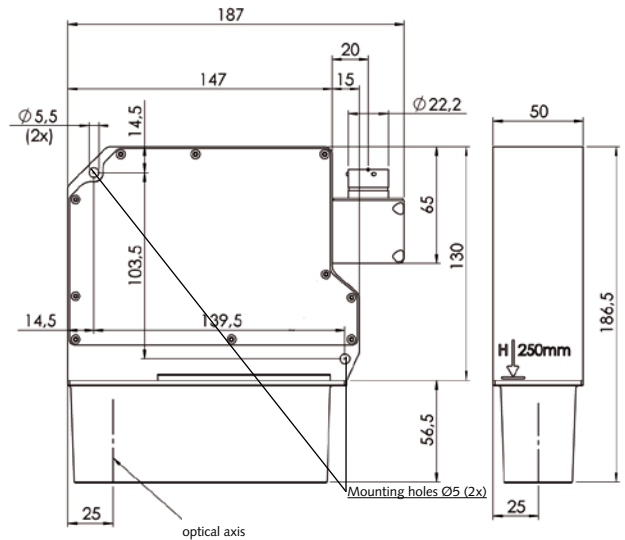


Fig. 3: Dimensions Correvit® S-HR sensor with 90° connector

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Mounting

With Kistler mounting equipment (see Optional Accessories).

When mounting the sensor at the vehicle, the mounting distance from the lower surface of the sensor body (not including the spray guard) to the road must be 250 ± 50 mm.

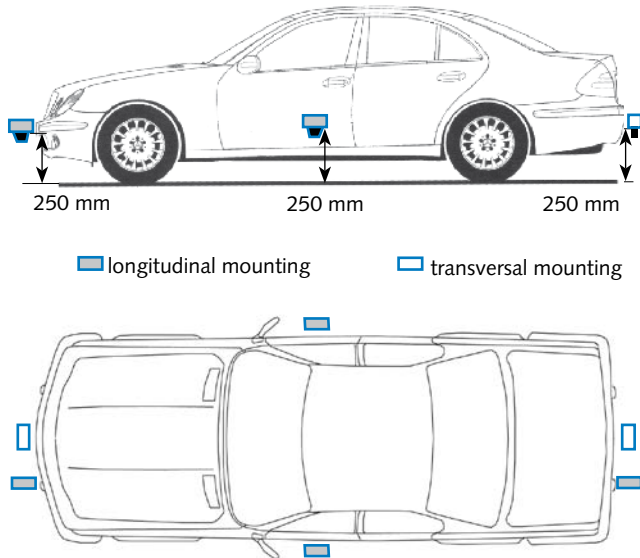


Fig. 4: Possible mounting positions

Ordering Key

| | | Type CSHRA |
|---------------------------------|---|------------|
| Sensor Head | | |
| Halogen* | 1 | □ |
| Sensor Cable | | |
| 2 m | 1 | □ |
| 5 m* | 2 | □ |
| 10 m | 3 | □ |
| Electronics | | |
| Standard* | 1 | □ |
| Interface Outputs | | |
| ± 10 V* | 1 | □ |
| ± 5 V | 2 | □ |
| Mounting Directions | | |
| Longitudinal* | 1 | □ |
| Transversal | 2 | □ |
| Longitudinal with 90° connector | 3 | □ |
| Transversal with 90° connector | 4 | □ |
| Interface Inputs | | |
| ± 10 V* | 1 | □ |

Included Accessories

- Power cable, l = 2 m
- Connection cable CAN, l = 2 m
- Connection cable RS-232C, l = 2 m
- Connection cable USB, l = 2 m
- Distribution cable, l = 1 m
- Transport case S-HR, complete
- Mini folding rule
- Multimedia-CD incl. Software & Manuals
- Sensor calibration
- Halogen lamp 20 W/12 V
- Tool to exchange the sensor halogen lamp
- Screw driver Torx T10
- Hexagon wrench 6 kt 4 mm
- Screw set S-HR
- Spray guard

Type/Art. No.

- KCD17360
- KCD13946
- KCD13425
- KCD13947
- KCD10527
- KCD17188
- KCD14643
- KCD11343
- KCD17167
- KCD14893
- KCD15437
- KCD15887
- KCD14283
- KCD17187
- KCD17117

Optional Accessories

- Suction holder S-HR
- Magnet holder S-HR

Type/Art. No.

- KCD17092
- KCD17091

Ordering Example*

Type CSHRA22111

S-HR sensor, standard halogen illumination, 5 m cable, standard electronics, interface outputs ± 10 V, longitudinal mounting direction, interface inputs ± 10 V

* Standard configuration

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